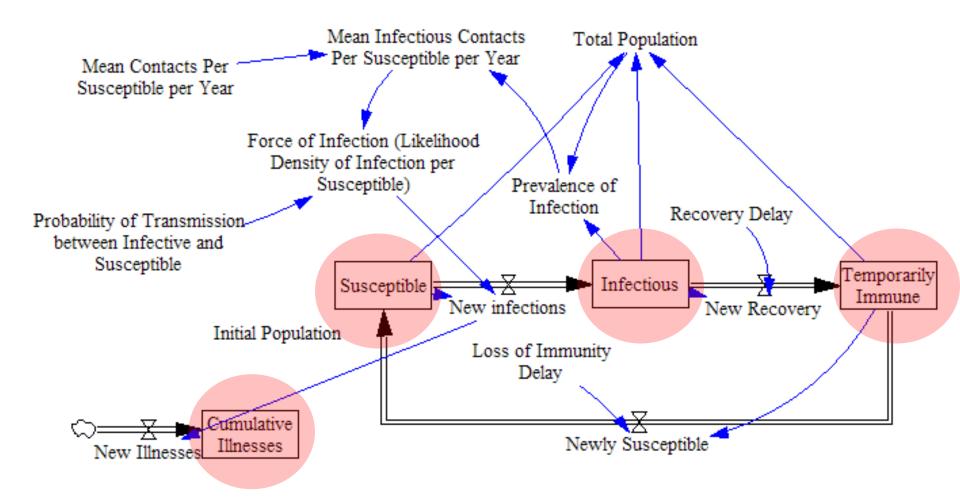
Stocks & Flows 2: First Order Delays & Aging Chains

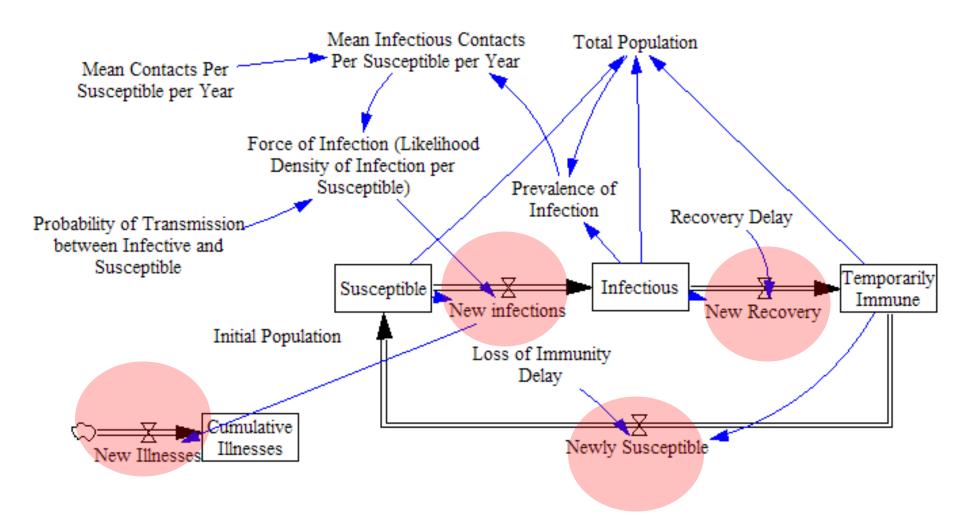
Nathaniel Osgood

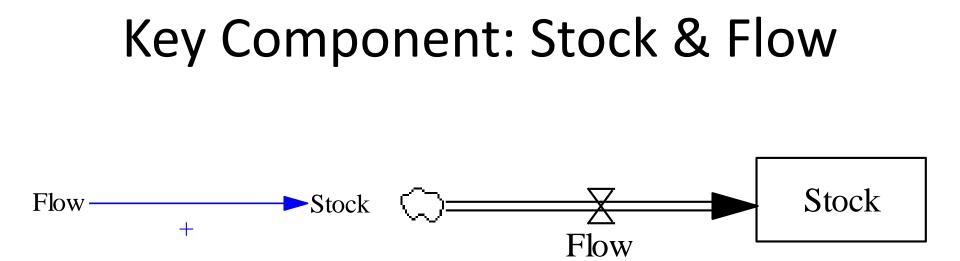
CMPT 858 FEBRUARY 1, 2011

Example Model: Stocks



Example Model: Flows

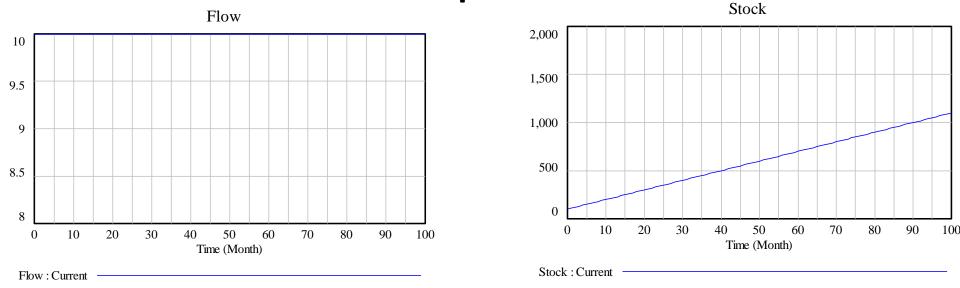




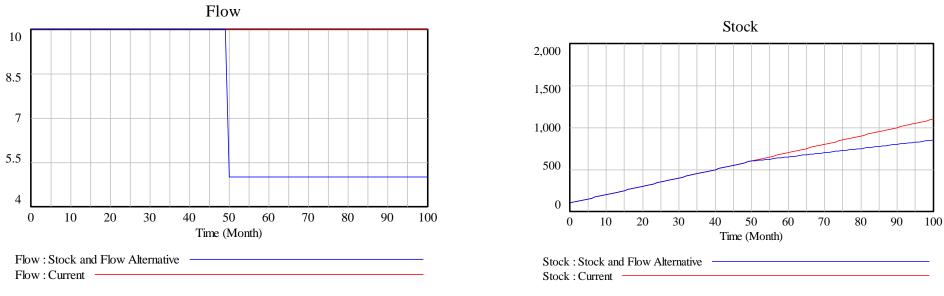
Structure & Behavior



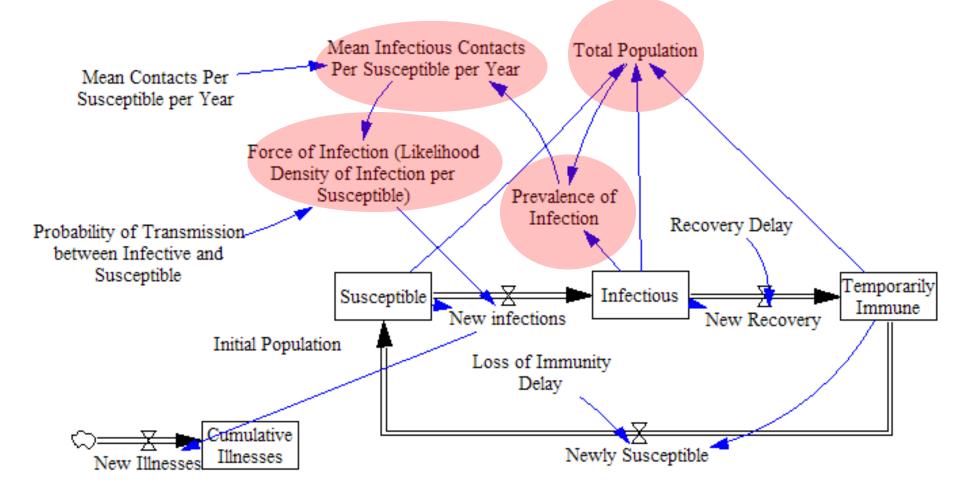
Net Flow Impact on Stock



Impact of Lowering Flow (Rate) to 5/Month?



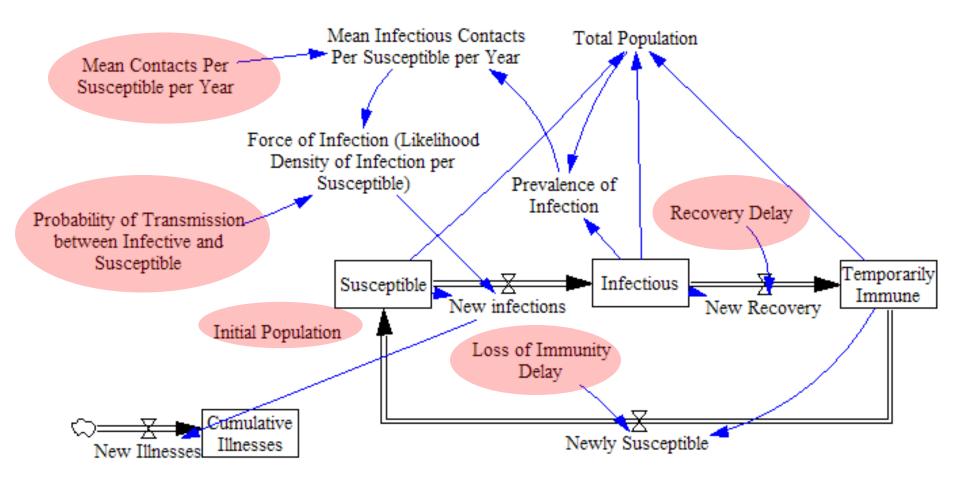
Example Model: Auxiliary Variables

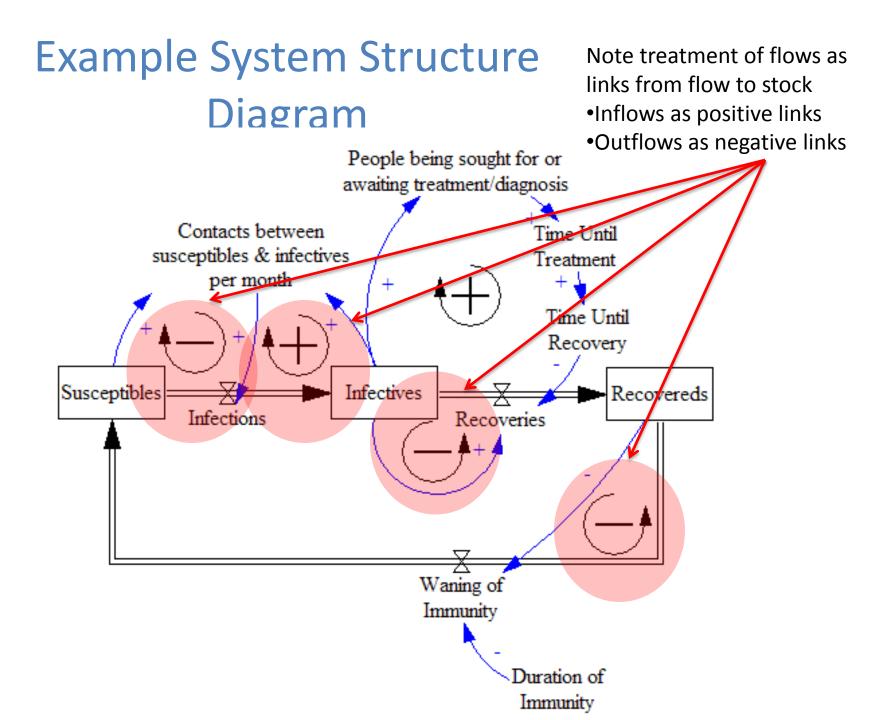


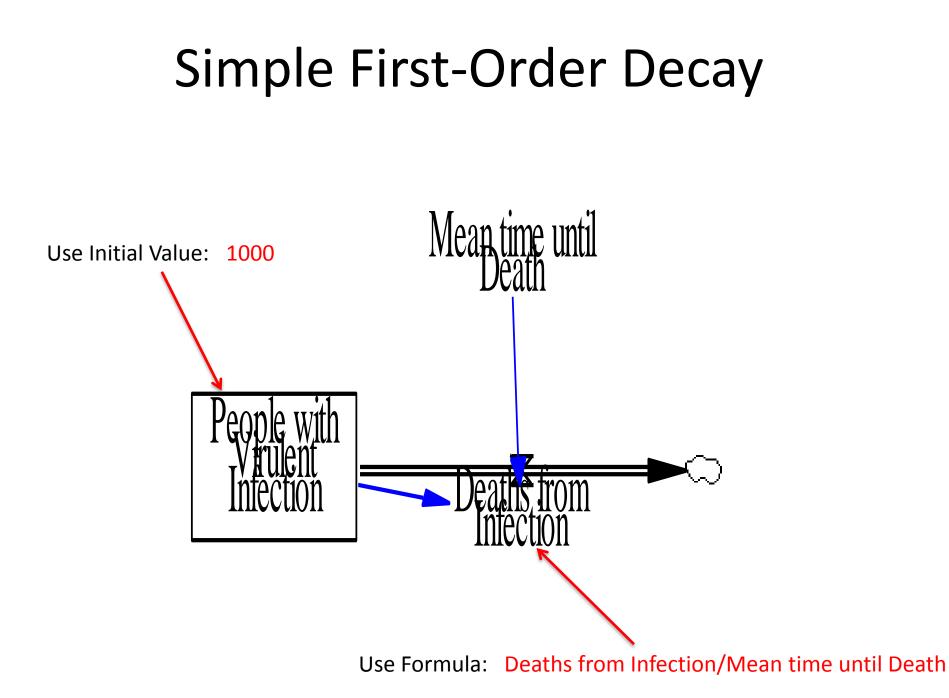
Constants & Time Series Parameters

- For similar reasons to auxiliary variables, we give names to
 - Model constants
 - Time series

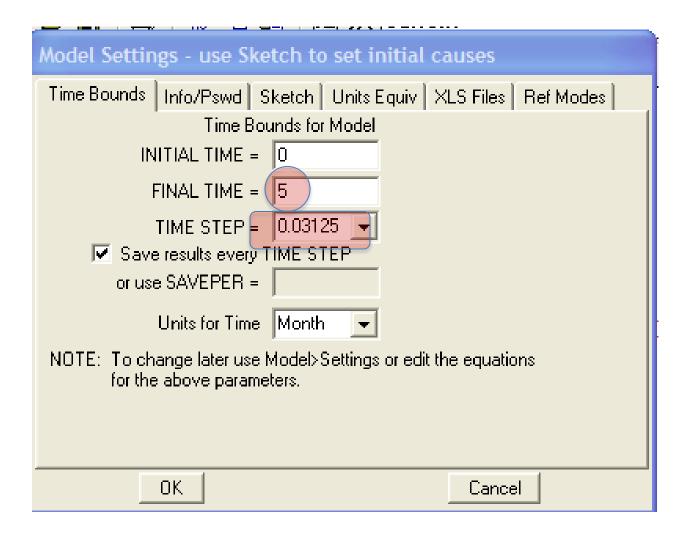
Example Model: Parameters



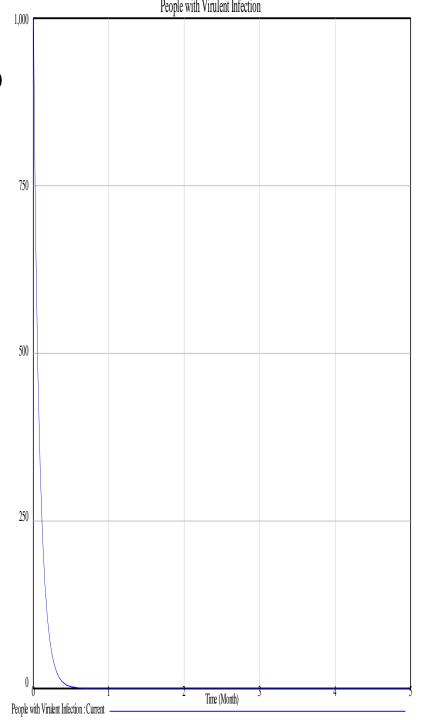




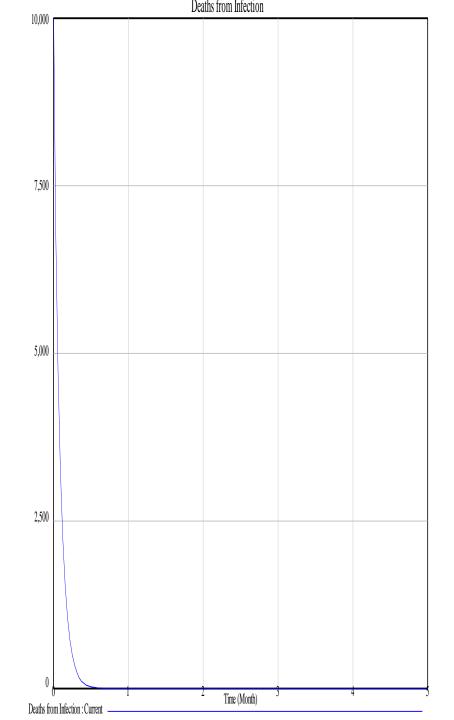
Set Model Settings (Model Menu/Settings Item)



Dynamics of Stock?



Dynamics of (Rate of) Death Flow?



Stocks As Accumulations

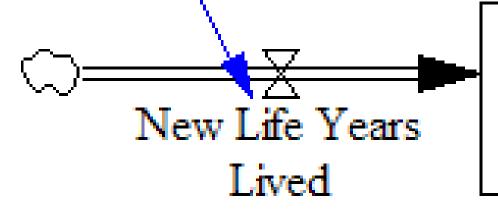
- We often use stocks to accumulate (integrate) other (evolving) quantities over time
- Example (assume time measured in years):

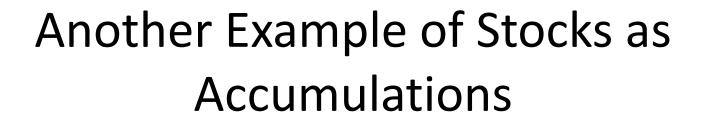
Current Population

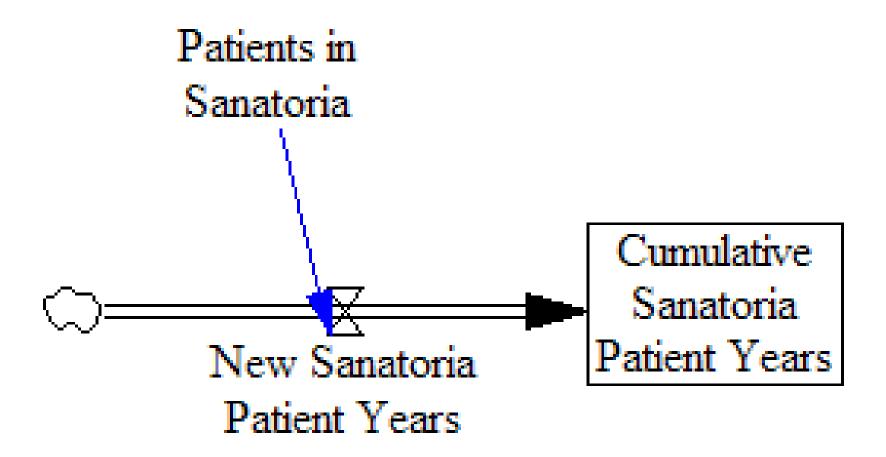
A Key Reflection: If we have population of size *P*, after 1 year, the stock holds 1**P*. After 2 years, 2*P, after *n* years, *n**P. With a changing P, this integrates P over time.

Cumulative Life

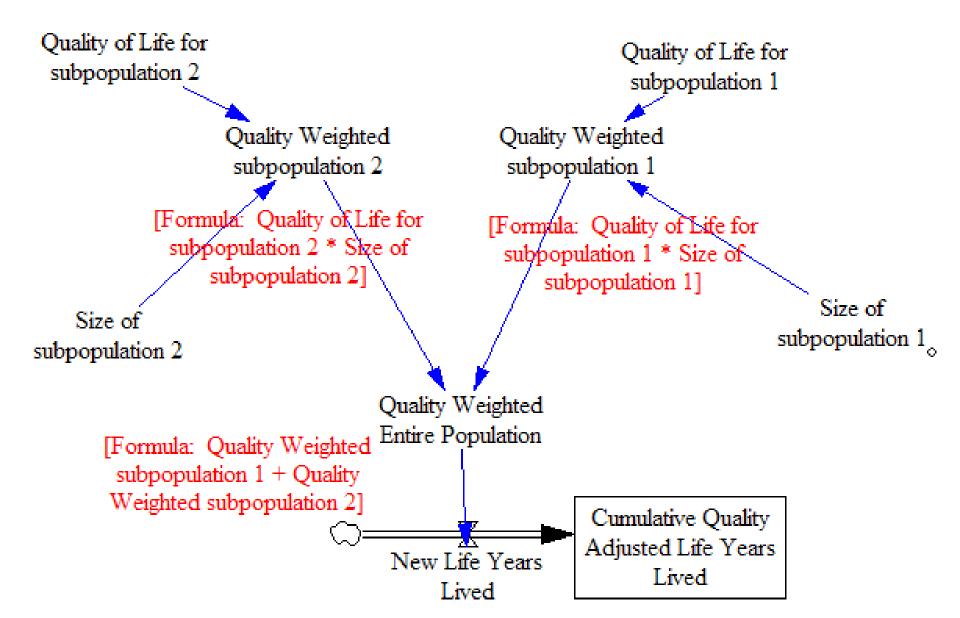
Years Lived







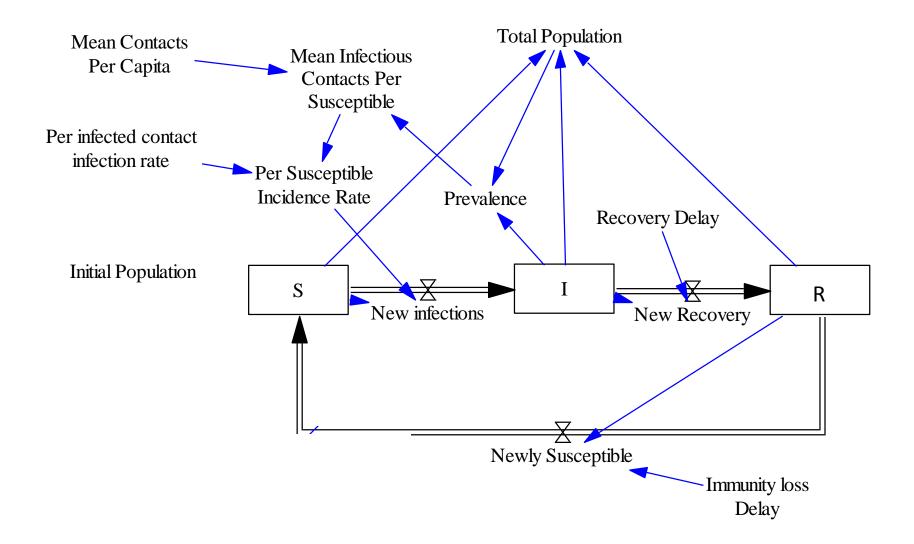
Slightly more Sophisticated



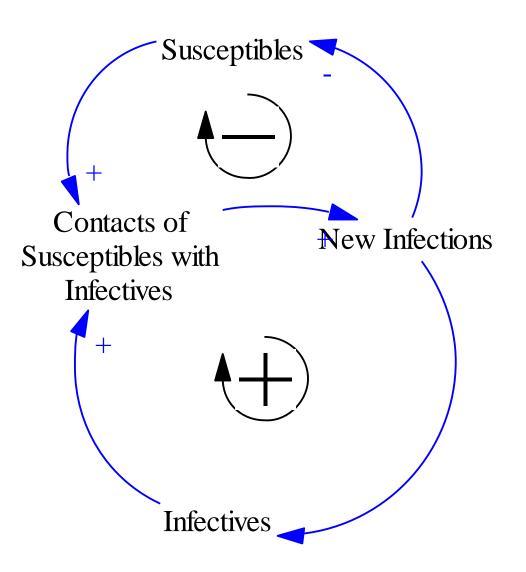
Principle: Structure Determines Behaviour

- Feedback & stock-and-flow structure of a system determines the possible patterns of behaviour
- Different sets of parameters (e.g. values for constants) will select particular behaviour within these behaviour patterns
- Changes to the feedback structure can change behaviour in fundamental ways

Simple SIT Model

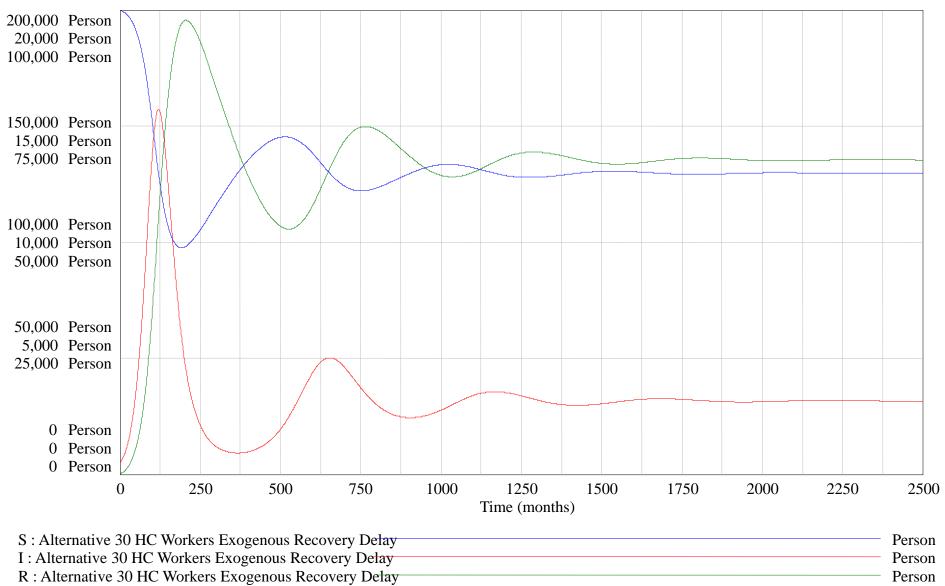


Classic Feedbacks

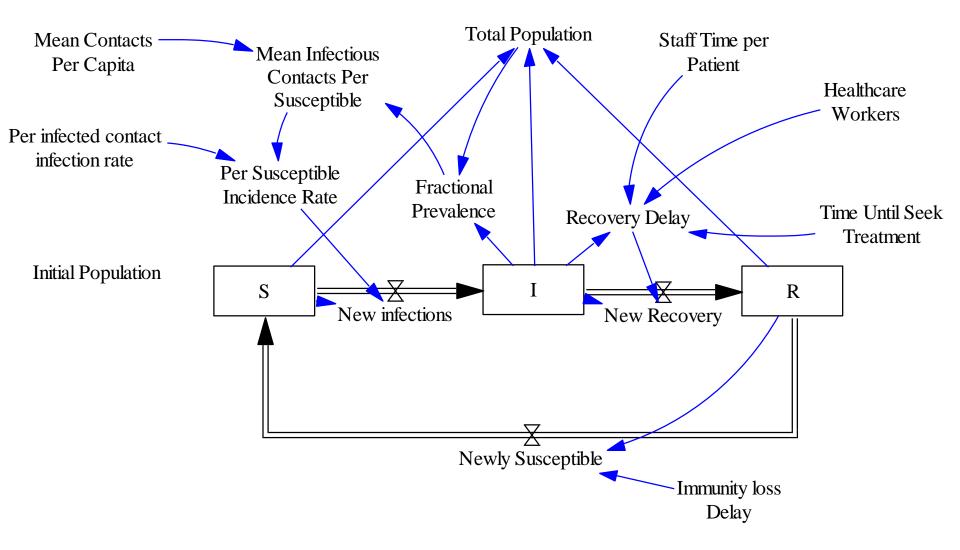


Dynamics

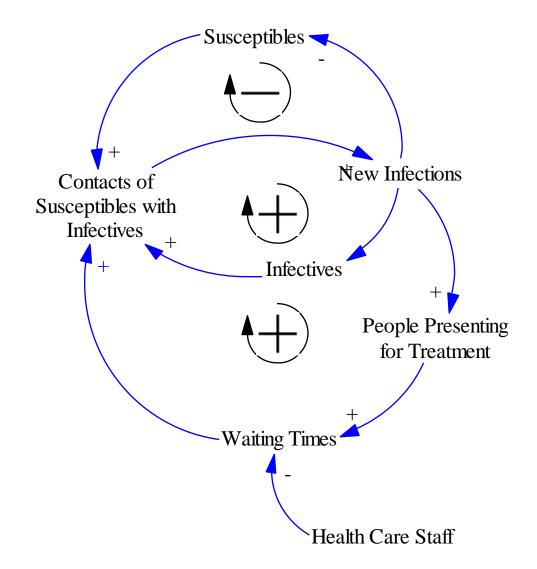
State variables over time



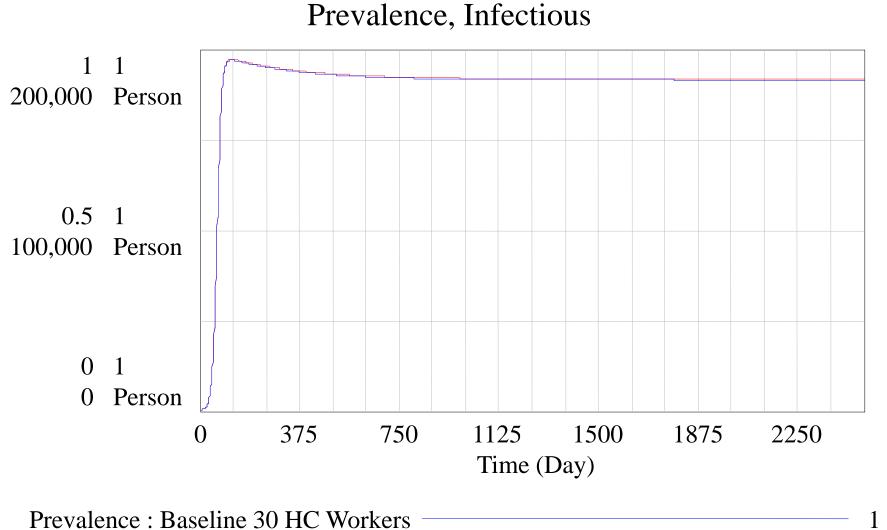
Broadening the Model Boundaries: Endogenous Recovery Delay



Broadening the Model Boundaries: Endogenous Recovery Delay



A Different Behaviour Mode



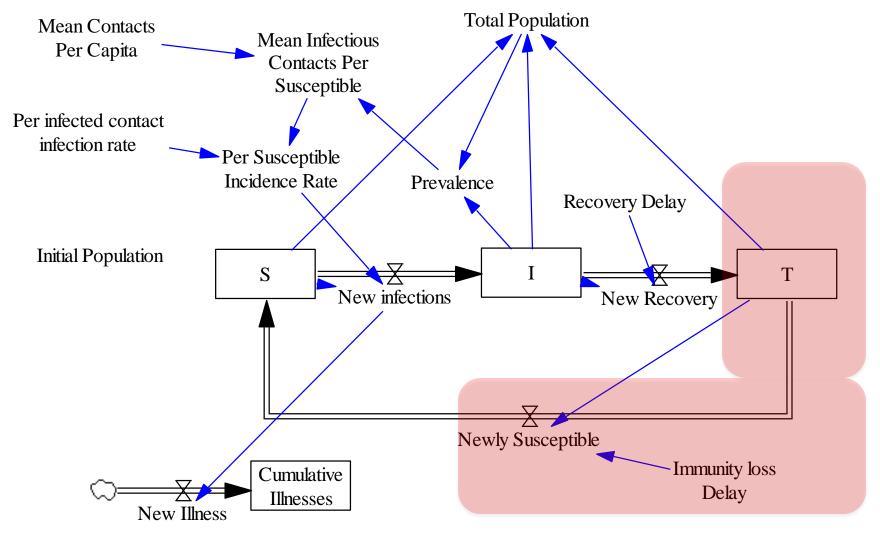
I : Baseline 30 HC Workers

Person

Structure as Shaping Behaviour

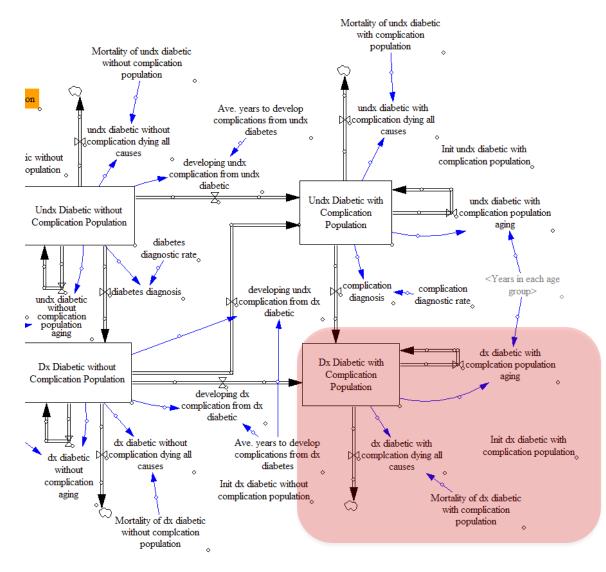
- System structure is defined by
 - Stocks
 - Flows
 - Connections between them
- Nonlinearity: The behaviour of the whole is more than the sum of the behaviour of the parts
 - "Emergent" behaviour would not be anticipated from simple behaviour of each piece in turn
- Stock and flow structure (including feedbacks) of a system determines the qualitative behaviour modes that the system can take on

First Order Delays in Action: Simple SIT Model



Department of Computer Science

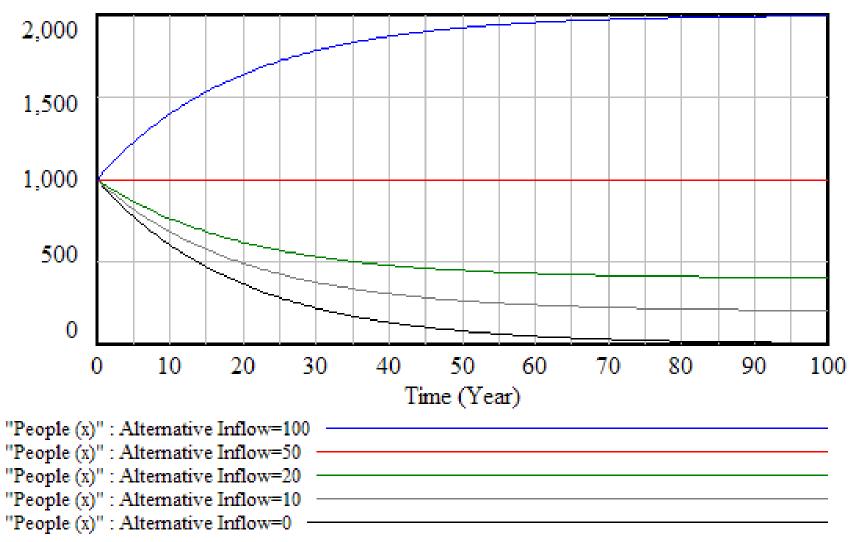
First Order Delays in Action: Simple SIT Model



Scenarios for First Order Delay: Variation in Inflow Rates

- For different immigration (inflows) (what do you expect?)
 - Inflow=10
 - Inflow=20
 - Inflow=50
 - Inflow=100
 - Why do you see this "goal seeking" pattern?
 - What is the "goal" being sought?

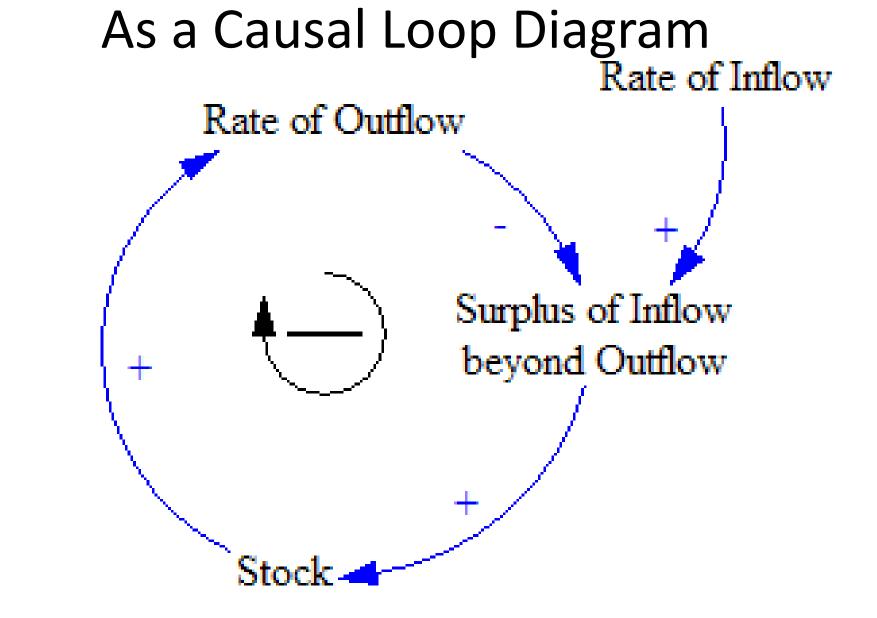
Behaviour of Stock for Different Inflows People (x)



Why do we see this behaviour?

Goal Seeking Behaviour

- The goal seeking behaviour is associated with a negative feedback loop
 - The larger the population in the stock, the more people die per year
- If we have more people coming in than are going out per year, the stock (and, hence, outflow!) rises until the point where inflow=outflows
- If we have fewer people coming in than are going out per year, the stock declines (& outflow) declines until the point where inflow=outflows



What does this tell us about how the system would respond to a sudden change in immigration?

Response to a Change

 Feed in an immigration "step function" that rises suddenly from 0 to 20 at time 50

Editing equation for - Immigration Rate					
Immigration Rate	Add Eq				
= if then else(Time < 50, 0, 20)	~				
Type Undo 7 8 9 + Variables Functions More Auxiliary {(())} 4 5 • Choose Variable Inputs Normal 1 2 × Time Time Units: • • • • •	•				
Comment	~				
Group: Ifirst order d 💌 Range: 🛛 🛛 🖌 Go To: Prev Next < Hilite	Sel New				
Errors: Equation OK	~				
OK Check Syntax Check Model Delete Variable	Cancel				

- Set the Initial Value of Stock to 0
- How does the stock change over time?

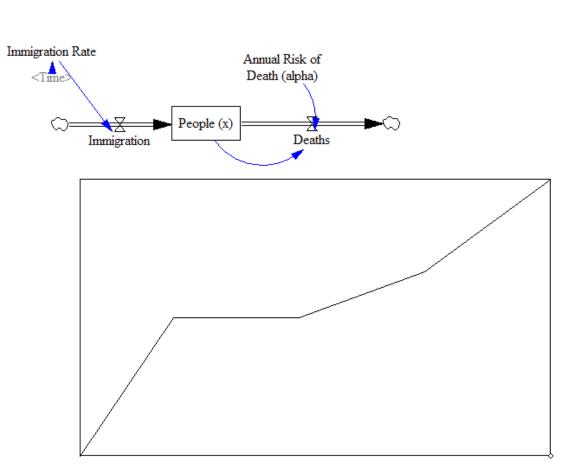
Create a Custom Graph & Display it as an Input-Output Object

Control Panel		
Variable Time Axis Scaling Datasets Graphs	Placeholders	
Rec Coord Redo Open Inflow_and_Outflow Custom Graphset Inflow_and_Outflow		
Open NewGS Save As Save		
Into Model Close Modify Open WIP Graph on Sim Display	Copy Delete	New Reorder
🔽 Keep on top		Close

• Editing

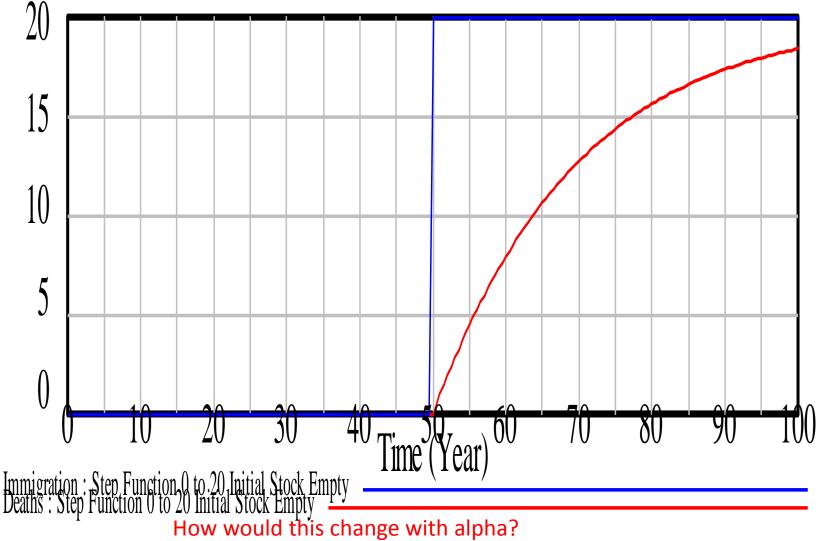
Name	Inflow_and_Outflow	Quick _	- Hide: 🕅	Title 🥅 🛛 Labe	el 🥅 Legend	
Title	Inflow and Outflow					
X-Axis		Sel	X Label			
X-min	X-max	X	divisions	🔲 Lbl-Interval	Y-div	
Stamp	mp Comment					
Туре	📀 Norm 🔿 Cum	C Stack	🗌 Dots 🔲 Fill	Width	Height	
Scale \	/ariable	Dataset	Label	LineW Units	Y-min Y-max	
	gration Sel					
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🗆 As W	'IP Graph (maxpoints)	Copy to	Test output	Soft Bounds	
	OK	As T	able	Car	ncel	

Create Input-Output Object (for Synthesim)



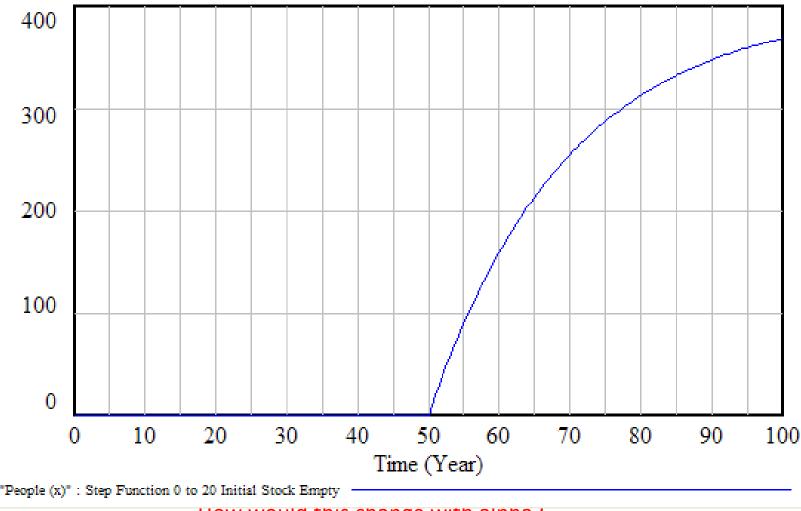
Input Output Object settings								
Object Type C Input Slider	C Output Workbench Tool			Output Custom Graph				
Variable name.	Choose:	Level.,		Auxiliary	Data.			
- Slider Settings Ranging from	0	to	100	with incre	ement			
				V L	abel with va	arname		
Custom Graph or Analysis Tool for Output								
Inflow_and_Outflow	W					-		
(ОК			Ca	ancel			

Stock Starting Empty Flow Rates Inflow and Outflow



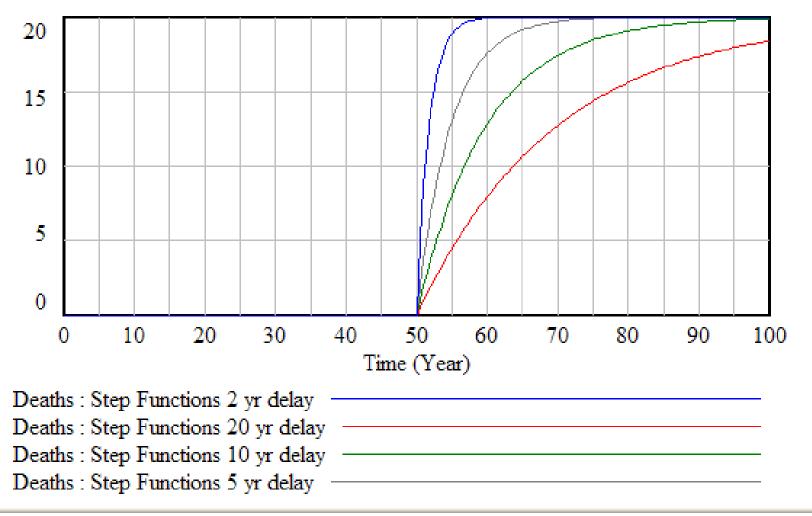
Stock Starting Empty? Value of *Stock* (Alpha=.05)

People (x)



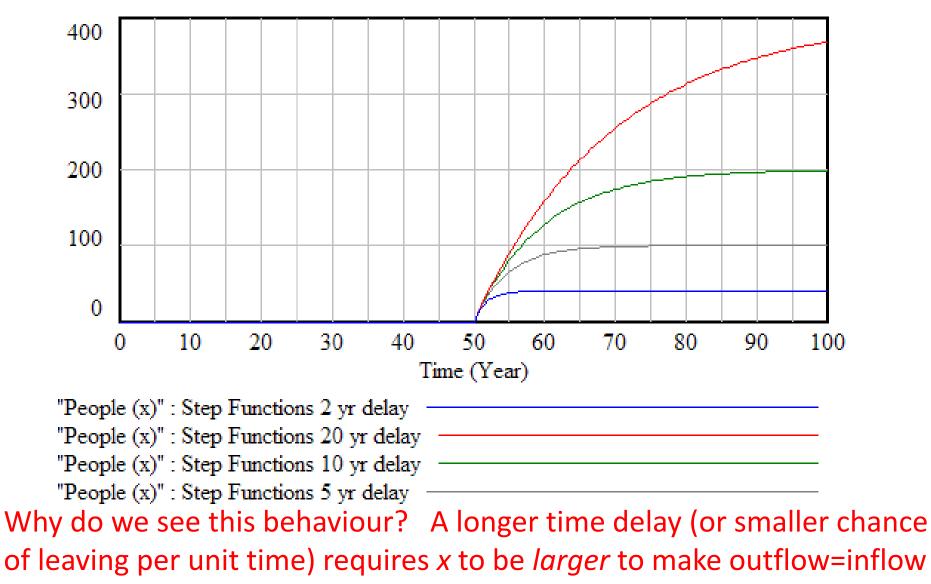
How would this change with alpha?

For Different Values of (1/) Alpha Flow Rates (Outflow Rises until = Inflow)

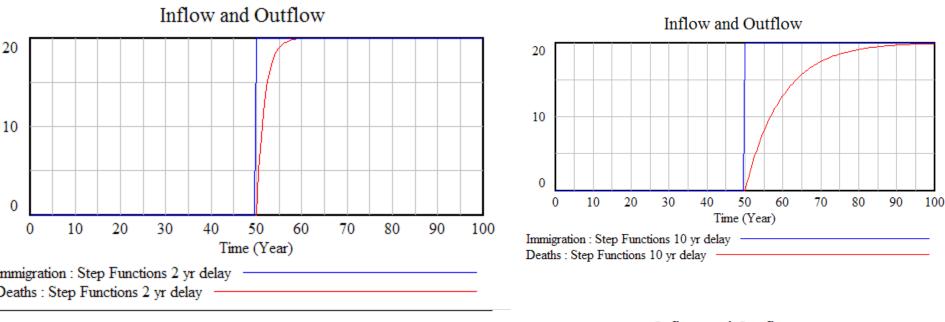


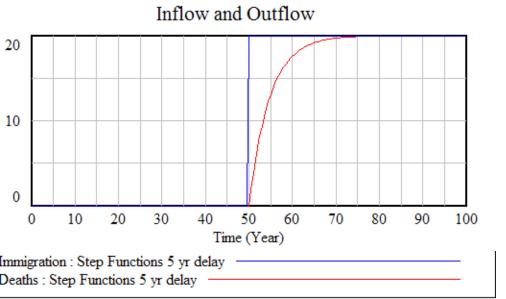
This is for the *flows*. What do stocks do?

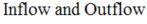
For Different Values of (1/) Alpha Value of Stocks

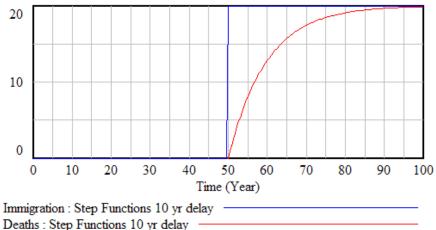


Outflows as Delaved Version of Inputs









Higher Order Delays & Aging Chains

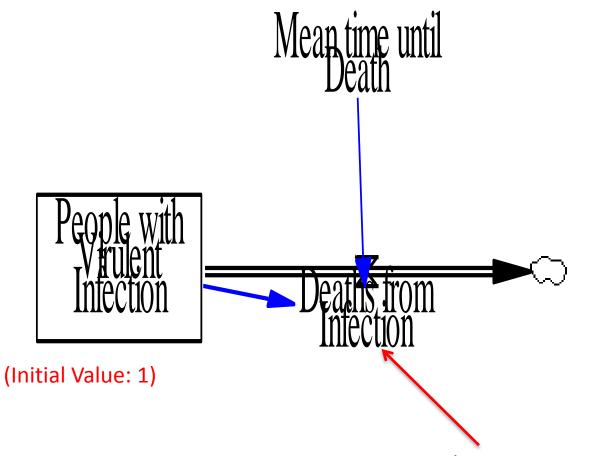
Moving Beyond the "memoryless assumption"

- Recall that first order delays assume that the pertime-unit risk of transitions to the outflow remains equal throughout simulation (i.e. are memoryless)
- Problem: Often we know that transitions are *not* "memoryless" e.g.
 - It may be the transition reflects some physical delays not endogeneously represented (e.g. Slow-growth of bacterial)
 - Buildup of "damage" of high blood sugars (Glycosylation)

Higher Orders of Delays

- We can capture different levels of delay (with increasing levels of fidelity) using cascaded series of 1st order delays
- We call the delay resulting from such a series of k
 1st order delays a "kth order delay"
 - E.g. 2 first order delays in series yield a 2nd order delay
- The behaviour of a kth order delay is a reflection of the behaviour of the 1st order delays out of which it is built
- To understand the behaviour of kth order delays, we will keep constant the mean time taken to transition across the entire set of all delays

Recall: Simple 1st Order Decay

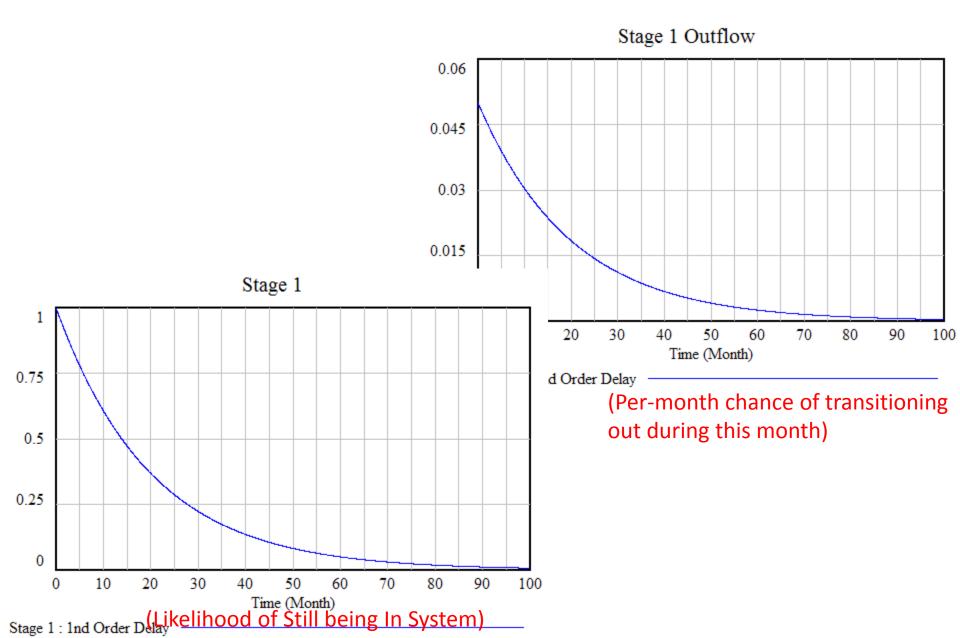


Use Formula: People with Virulent Infection/Mean time until Death

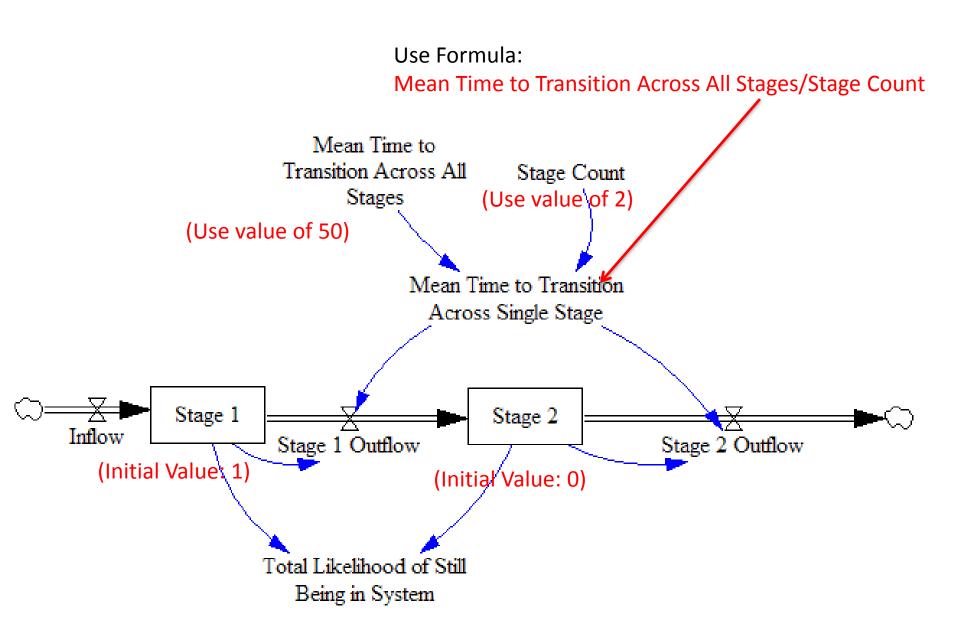
Recall: 1st Order Delay Behaviour

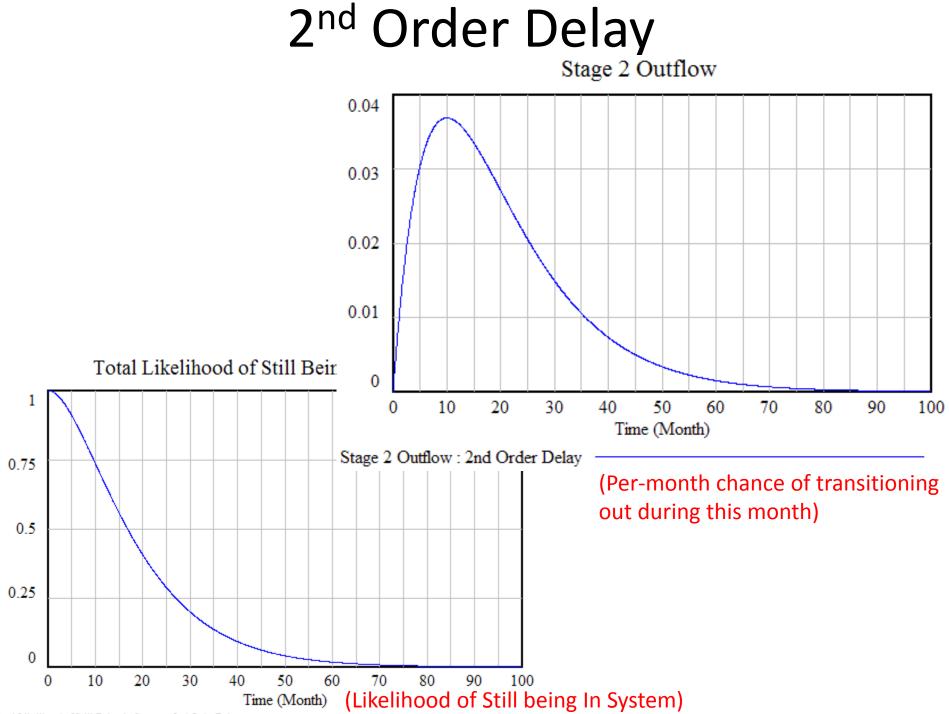
- Conditional transition prob: For a 1st Order delay, the per-time-unit likelihood of leaving given that one has not yet left the stock remains constant
- Unconditional transition prob: For a 1st Order delay, the unconditional per-time-unit likelihood of leaving declines exponentially
 - i.e. if were were originally in the stock, our chance of having left in the course of a given time unit (e.g. month) declines exponentially
 - This reflects the fact that there are fewer people who could still leave during this time unit!

Recall: 1st Order Delay Behaviour



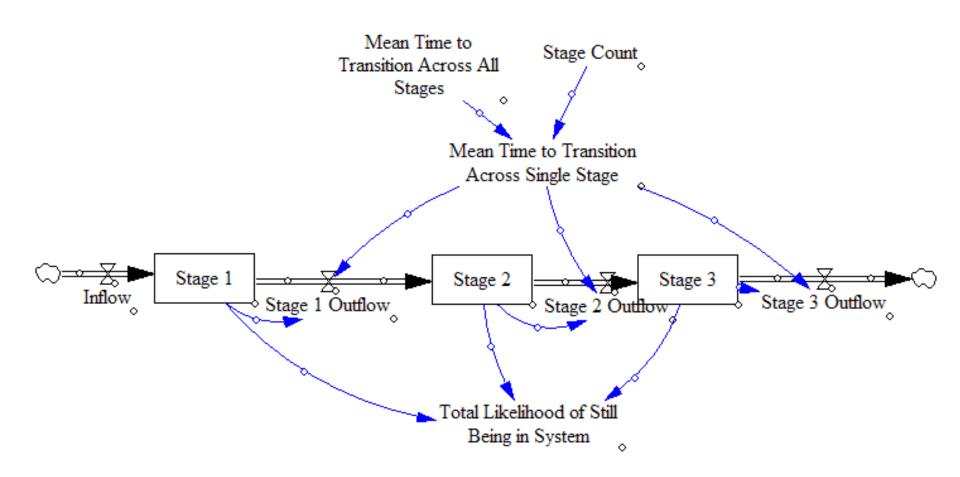
2nd Order Delay

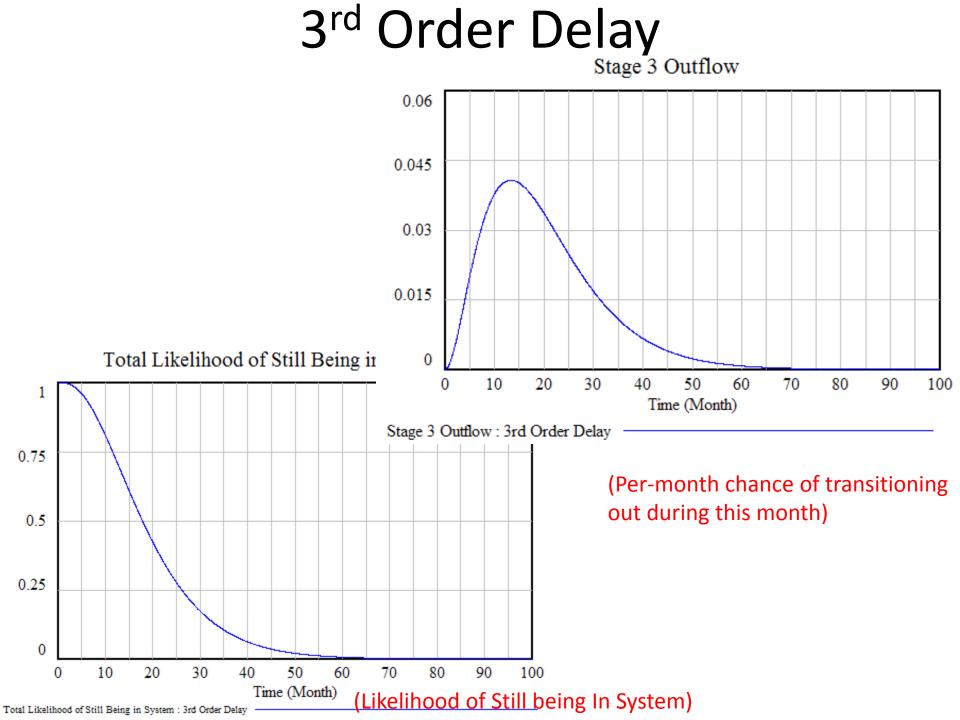


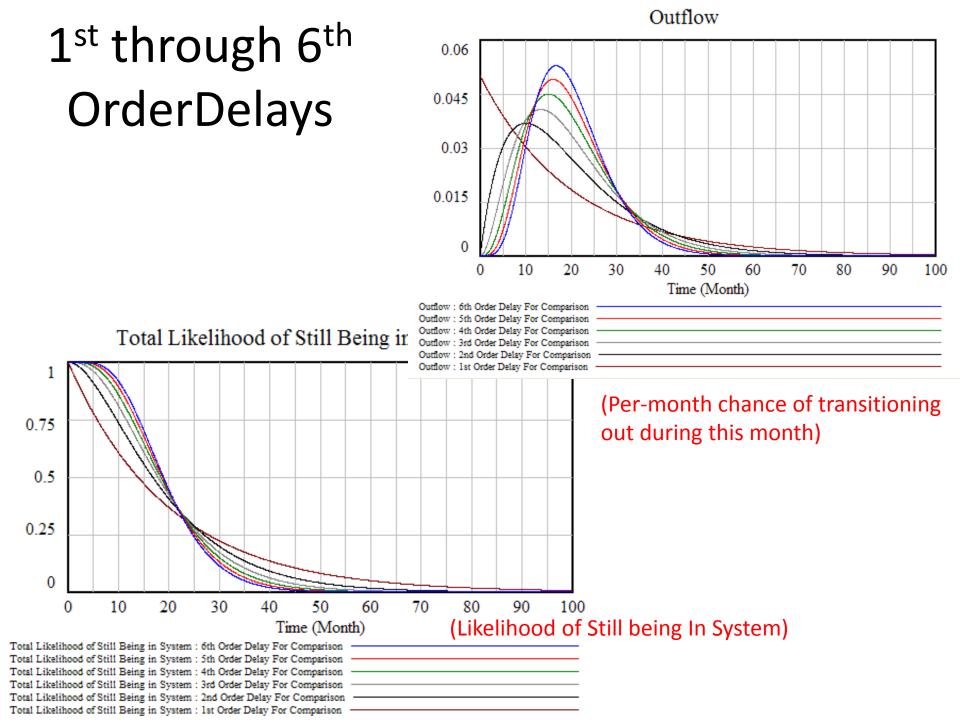


Total Likelihood of Still Being in System : 2nd Order Delay

3rd Order Delay







Mean Times to Depart Final Stage

- Mean time of k stages is just k times mean time of one stage (e.g. if the mean time for leaving 1 stage requires time μ, mean time for k = k*μ
- In our examples, as we added stages, we reduced the mean time per stage so as to keep the total constant!
 - i.e. if we have k stages, the mean time to leave each stage is
 1/k times what it would be with just 1 stage
- Infinite order delay: As we add more and more stages (k→∞), the distribution of time to leave the last stage approaches a normal distribution
 - If we reduce the mean time per stage so as to keep the total time constant, this will approach an impulse function
 - This indicates an exactly fixed time to transition through all stages!

Distribution of Time to Depart Final Stage

- The distributions for the total time taken to transition out of the last of k stages are members of the *Erlang*distribution family
 - These are the same as the distribution for the kth interarrival time of a Poisson process
- k=1 gives exponential distribution (first order delay)
- As k→∞, approaches normal distribution (Gaussian pdf)

0 4	4 U O IU 12 14 IU 10 20
Parameters	$k>0 \in \mathbb{Z}$ shape $\lambda>0$ rate (real) alt.: $ heta=1/\lambda>0$ scale (real)
Support	$x \in [0; \infty)$
Probability density function (pdf)	$\frac{\lambda^k x^{k-1} e^{-\lambda x}}{(k-1)!}$
Cumulative distribution function (cdf)	$\frac{\gamma(k,\lambda x)}{(k-1)!} = 1 - \sum_{n=0}^{k-1} e^{-\lambda x} (\lambda x)^n / n!$
Mean	k/λ
Median	no simple closed form
Mode	$(k-1)/\lambda$ for $k\geq 1$
Variance	k/λ^2
Skewness	$\frac{2}{\sqrt{k}}$
Excess	6
kurtosis	\overline{k}
Entropy	$\begin{aligned} &(1-k)\psi(k) + \ln \frac{\Gamma(k)}{\lambda} + k \\ &(1-t/\lambda)^{-k} \text{for } t < \lambda \end{aligned}$
Moment- generating function (mgf)	$(1-t/\lambda)^{-k}$ for $t<\lambda$
Characteristic function	$(1 - it/\lambda)^{-k}$

From Wikipedia, 2009

"Aging Chains" (including successive 1st Order Delays & Competing Risks) in our Model of Chronic Kidnev Disease

